

Spot is a four-legged, dog-like robot with high levels of autonomy. It uses multiple sensors and motors to navigate its environment while also maintaining its balance. The purpose of this study is to develop a simplified manual for Spot and to give new users a set of simple instructions to be able to comfortably operate Spot. This is significant because many people are introduced to Spot and have no clue how to operate it. We will use written guides, checklists and videos, to give instructions on how to properly operate Spot. Using these methods will give new users familiarity with Spot and give them the knowledge they need to successfully control it.